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SCI, SSCI ve AHCI İndekslerine Giren Dergilerde Yayınlanan Makaleler

- I. **Variability in locomotor dynamics reveals the critical role of feedback in task control.**
Uyanik İ., Sefati S., Stamper S., Cho K., Ankarali M., Fortune E., Cowan N.
eLife, cilt.9, 2020 (SCI İndekslerine Giren Dergi)
- II. **Frequency-Domain Subspace Identification of Linear Time-Periodic (LTP) Systems**
Uyanik İ., SARANLI U., ANKARALI M. M. , Cowan N. J. , Morgul O.
IEEE TRANSACTIONS ON AUTOMATIC CONTROL, cilt.64, sa.6, ss.2529-2536, 2019 (SCI İndekslerine Giren Dergi)
- III. **Harmonic transfer functions based controllers for linear time-periodic systems**
Hidir E. K. , Uyanik İ., Morgul O.
TRANSACTIONS OF THE INSTITUTE OF MEASUREMENT AND CONTROL, cilt.41, sa.8, ss.2171-2184, 2019 (SCI İndekslerine Giren Dergi)
- IV. **Sensory Cues Modulate Smooth Pursuit and Active Sensing Movements**
Uyanik İ., Stamper S. A. , Cowan N. J. , Fortune E. S.
FRONTIERS IN BEHAVIORAL NEUROSCIENCE, cilt.13, 2019 (SCI İndekslerine Giren Dergi)
- V. **State-space identification of switching linear discrete time-periodic systems with known scheduling signals**
Uyanik I., Hamzacebi H., ANKARALI M. M.
TURKISH JOURNAL OF ELECTRICAL ENGINEERING AND COMPUTER SCIENCES, cilt.27, sa.4, ss.2755-2768, 2019 (SCI İndekslerine Giren Dergi)
- VI. **Enhancing 3D range image measurement density via dynamic Papoulis-Gerchberg algorithm**
Kuzucu E., Ozturk D., Gul M., Ozbay B., Arisoy A. M. , Sirin H. O. , Uyanik İ.
TRANSACTIONS OF THE INSTITUTE OF MEASUREMENT AND CONTROL, cilt.40, sa.16, ss.4407-4420, 2018 (SCI İndekslerine Giren Dergi)
- VII. **A low-cost feedback control systems laboratory setup via Arduino-Simulink interface**
Uyanik İ., Catalbas B.
COMPUTER APPLICATIONS IN ENGINEERING EDUCATION, cilt.26, sa.3, ss.718-726, 2018 (SCI İndekslerine Giren Dergi)
- VIII. **Identification of a vertical hopping robot model via harmonic transfer functions**
Uyanik İ., Ankarali M. M. , Cowan N. J. , SARANLI U., Morgul O.
TRANSACTIONS OF THE INSTITUTE OF MEASUREMENT AND CONTROL, cilt.38, sa.5, ss.501-511, 2016 (SCI İndekslerine Giren Dergi)
- IX. **Experimental Validation of a Feed-Forward Predictor for the Spring-Loaded Inverted Pendulum Template**
Uyanik İ., Morgul O., SARANLI U.
IEEE TRANSACTIONS ON ROBOTICS, cilt.31, sa.1, ss.208-216, 2015 (SCI İndekslerine Giren Dergi)

Atıflar

Toplam Atıf Sayısı (WOS):40

h-indeksi (WOS):4